# **PFR-1550 LOAD CONTROL INSTALLATION, SET UP AND ADJUSTMENT**

The Model PFR-1550 monitors the true power going to a motor. By sensing power (volts x amps x power factor) rather than just amps, there is much greater sensitivity. It has one adjustable trip point which can be either:

High - Relay swithces when load is above the trip point Low - Relay switches when load is below the trip point.

### MOUNTING

HP

LOAD CONTROLS

INCORPORATE

MODEL PFR-1550

TRIF

DELAY

HIGH

1.OW START KW

Wiring is done to un-pluggable terminal strips on the rear of the unit. Three ways to mount:

- On door or raceway use cutout template
- Panel Mount use template + optional Bezel Kit (No Charge)
- On wall on standard outdoor junction box + optional **Outlet Box Adapter (No Charge)**

# VOLTAGE

120 volts AC is taken from two of the phases. If the motor starter already has a 120-volt control transformer with 10VA of free capacity, it can be used. Otherwise, install a separate transformer. It is okay if the secondary is grounded. BE SURE TO NOTE WHICH TWO PHASES SUPPLY THE TRANSFORMER.

In 120/208V three-phase system, the 120V MUST come from a transformer connected to two of the phases. The 120V phase to ground voltage cannot be used.

# CURRENT

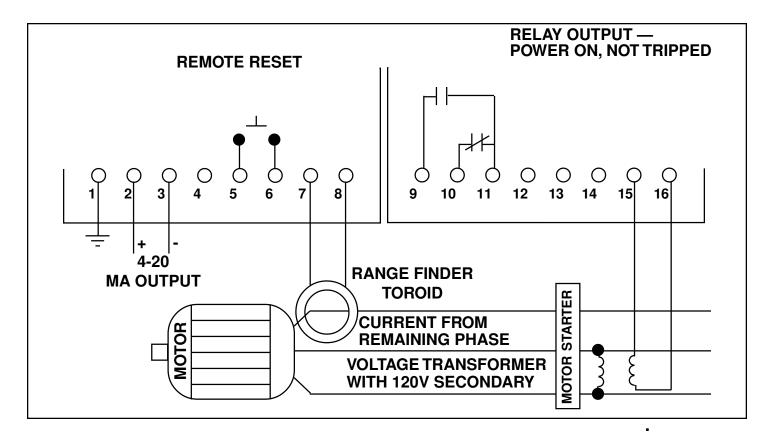
The current signal is taken from the REMAINING phase. This current sample passes through the Range Finder Toroid.

It is VERY IMPORTANT that the current signal comes from the phase that IS NOT supplying the 120V control transformer. Be extra careful when the machine has reversing starters or multi-speed windings. If a wrong phase is used the control will either:

Work backwards Have reduced sensitivity

If you are using a variable frequency drive, use a different control. Call LOAD CONTROLS, INC. for help.





### **FULL SCALE CAPACITY AT 460 VOLTS**

The Range Finder Toroid has six motor size choices. Select one that is equal or larger than your motor. This will leave some headroom.

- For motors less than 5 HP (460 volt), take extra turns.
- For motors greater than 50 HP, use Range Finder Toroid + Current Transformer.

| MOTOR  | FULL              | % FULL |                  | TURNS |                  |
|--------|-------------------|--------|------------------|-------|------------------|
| SIZE   | SCALE<br>CAPACITY | LOAD   | FINDER<br>SWITCH |       | TRANS-<br>Former |
|        | CAPACITY          |        | зинсп            |       | FORMER           |
| 1/2 HP | .6 HP             | 123    | 2 ON             | 8     |                  |
| 1      | 1.25              | 123    | 2 ON             | 4     |                  |
| 1-1/2  | 1.65              | 109    | 2 ON             | 3     |                  |
| 2      | 2.70              | 134    | 2 ON             | 2     |                  |
| 3      | 3.80              | 128    | 3 ON             | 2     |                  |
| 5      | 5.50              | 110    | 2 ON             | 1     |                  |
| 7-1/2  | 8.25              | 110    | 3 ON             | 1     |                  |
| 10     | 11.0              | 110    | 4 ON             | 1     |                  |
| 15     | 27.5              | 183    | 5 ON             | 1     |                  |
| 20     | 27.5              | 137    | 5 ON             | 1     |                  |
| 25     | 27.5              | 110    | 5 ON             | 1     |                  |
| 30     | 55.0              | 183    | 6 ON             | 1     |                  |
| 40     | 55.0              | 138    | 6 ON             | 1     |                  |
| 50     | 55.0              | 110    | 6 ON             | 1     |                  |
| 60     | 84.0              | 140    | 1 ON             | 1     | 100:5            |
| 75     | 84.0              | 112    | 1 ON             | 1     | 100:5            |
| 100    | 130               | 130    | 1 ON             | 1     | 150:5            |
| 125    | 130               | 104    | 1 ON             | 1     | 150:5            |
| 150    | 173               | 115    | 1 ON             | 1     | 200:5            |
| 200    | 216               | 108    | 1 ON             | 1     | 250:5            |
| 250    | 260               | 104    | 1 ON             | 1     | 300:5            |
| 300    | 346               | 115    | 1 ON             | 1     | 400:5            |
| L      |                   |        |                  |       |                  |

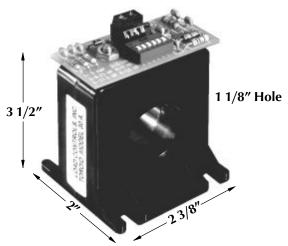
### **MULTIPLIERS**

| For nominal voltages other than 460 volts,<br>multiply 460V full scale by: |  |  |  |  |
|--|--|--|--|--|
| 208V = .45   |  |  |  |  |
| 230V = .5  |  |  |  |  |
| 380V = .83   |  |  |  |  |
| 415V = .9  |  |  |  |  |
| 575V = 1.25  |  |  |  |  |
| For Kilowatts multiply Full Scale HP x .746                                |  |  |  |  |

### For motor sizes or capacities not in table:

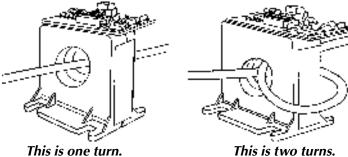
% Full Load =  $\frac{\text{Full Scale Capacity}}{\text{Your Motor Size}} \times 100$ 

# **RANGE FINDER TOROID**



FOR MOTORS LESS THAN 5 HP

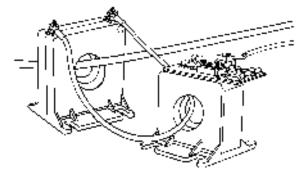
Take more "turns" of the leg through the Toroid. Each time the wire passes through the Toroid is a "turn".



This is two turns.

# FOR MOTORS GREATER THAN 50 HP

A Current Transformer is used to reduce the primary current. The 5-amp secondary passes through the Toroid.



Pass secondary of CT through toroid.

# CAUTION

When current is flowing through the primary of the external current transformer, always have a wire between the two brass Terminals on the CT.

If they are left open, dangerous and destructive voltages can develop.

# **HOOKING UP THE RESET**

Control can be reset three ways:

- Manually with the Reset button on the control.
- Remotely with a remotely located reset button or relay.
- Automatic with a jumper.

### **Remote Reset-**

Momentarily connect Terminal 5 to Terminal 6.

**Automatic Reset-Jumper Terminal 5 to Terminal 6.** 

The terminals for Reset generate a small amount of current (8-12 milliamps). To reset, you just need to connect the terminal to the circuit common (Terminal 6).

The switches or relays that you use must be suitable for low current (Gold flashed contacts, Reed Relays, Mercury Switches).

### **4-20 MILLIAMP ANALOG OUTPUT**

The Analog Output is directly proportional to Full Scale capacity. It is always active. 500 ohm maximum connected impedance.

| Terminal 2 | 4-20mA | Positive |
|------------|--------|----------|
| Terminal 3 | 4-20mA | Negative |

Use twisted pair or in noisy environments, use shielded cable. Ground shield at other end.

Use the Full Scale capacity from the chart to scale external meter, chart recorders or computers.

### THE PFR-1550 POWERS THE 4-20MA SIGNAL. DON'T USE AN EXTERNAL DC POWER SUPPLY.

# **SPECIFICATIONS PFR-1550**

### **ENCLOSURE**

Glass-filled Polycarbonate NEMA 4, 4X - STYLE (3 1/4" x 6 1/4" x 2") (83 mm x 160 mm x 54 mm)

### CAPACITY

To 50 horsepower directly through Toroid To 500 horsepower with external **Current Transformer & Toroid** 

**DIGITAL LOAD DISPLAY** .4" LED 3 Digit

#### **RELAY OUTPUT**

Form C 3 AMP @ 300 VAC or 1/8 HP @ 240 VAC Latch when tripped

### ANALOG OUTPUT

4-20mA; powered by the PFR-1550 500 OHM maximum connected impedance

#### **RESPONSE TIME** 25 Milliseconds

TEMPERATURE 0ºC - 55ºC

#### TIMERS

Start-up and Trip Delay 0-90 second 0-2 second in .1 second increments 2-90 second in 1 second increments

# **TO SET FULL SCALE**

- After hook-up, find your HP, KW or % from the chart.
- Decide if you want to display HP, % or KW.
- The scale cycles through the choices shown below and blinks slowly for each choice. Each press of scale moves you to the next choice.

# FRONT PANEL SET-UP TIPS

- 1) None of the settings will be changed until you hold down  $\overline{(ENTER)}$  and the fast blinking stops.
- 2) Five seconds after you have pressed a button, the Control will return to normal operation.
- 3) If you hold down the digits will continue to change.
- 4) You only need to do scale when you install the Control (or if you change the hook-up).

| DIGITS $\rightarrow$      | $\begin{array}{l} DECIMAL \rightarrow \\ XXX. \end{array}$ | $\begin{array}{l} DECIMAL \rightarrow \\ XX.X \end{array}$ | $\begin{array}{l} DECIMAL \rightarrow \\ X.XX \end{array}$ | $HP \rightarrow$                    | % →                                 | KW                                  |
|---------------------------|--|--|--|-------------------------------------|-------------------------------------|-------------------------------------|
| to change                 | if this is<br>your choice,<br>press                        | if this is<br>your choice,<br>press                        | if this is<br>your choice,<br>press                        | if this is<br>your choice,<br>press | if this is<br>your choice,<br>press | if this is<br>your choice,<br>press |
| $\downarrow$              | $\downarrow$   | $\downarrow$   | $\downarrow$   | $\downarrow$                        | $\downarrow$                        | $\downarrow$                        |
| ENTER                     | ENTER  | ENTER  | ENTER  | ENTER                               | ENTER                               | ENTER                               |
| until fast<br>blink stops | until fast<br>blink stops                                  | until fast<br>blink stops                                  | until fast<br>blink stops                                  | until fast<br>blink stops           | until fast<br>blink stops           | until fast<br>blink stops           |

# TO VIEW AND CHANGE THE SET POINTS AND DELAY TIMES

cycles through the choices. The LED for each choice will turn ON.

To change a setting, use



Press ENTER until quick blinking stops to store your new choice.

After 5 seconds if you haven't pressed any buttons, control will return to normal operation.

For High Trip - Relay will switch when load is ABOVE the Set Point.

Press U Juntil display shows HHH

Hold **ENTER** until high LED stops blinking

For Low Trip - Relay will switch when load is BELOW the

Set Point.

Press until display shows LLL

Hold **ENTER** until low LED stops blinking

The High or Low LED will remain on during normal operation.



# Start-up Timer

The Start-up Timer bypases the Control during motor start-up to avoid false trips because of current inrush. For convenience, the TIMING BEGINS WHEN THE MOTOR STARTS. The Start-up LED stays lit until the start-up period is over.

The start-up time should be:

• Long enough so that the load has stabilized.

To bypass Start-up Timer set time to zero seconds.

# **Delay Timers**

To avoid nuisance trips from short overloads, Delay Timers bypass the Control for the selected time. The relays won't trip until the time is exceeded. If the trip condition goes away before the time is up, the timer resets to zero.

 Start with minimum Delay. If you are getting trips where you don't want them, increase the Delay Time.

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